

# WEST Search History

DATE: Saturday, April 05, 2003

<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>	<u>Set Name</u>
			result set
side by side			
	<i>DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
L3	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and handle and zeus or (divinci or di vinci)	59	L3
L2	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle	88	L2
L1	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	L1

END OF SEARCH HISTORY

Set Name Query  
side by sideHit Count Set Name  
result set

*DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ*

<u>L3</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and handle and zeus or (divinci or di vinci)	59	<u>L3</u>
<u>L2</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle	88	<u>L2</u>
<u>L1</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	<u>L1</u>

END OF SEARCH HISTORY

[Back to Previous Page](#)**First experience with colliding electron-proton beams in HERA***Brinkmann, R.; Willeke, F.;*

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